

Robot Learning

5. RANSAC

Jeong-Yean Yang

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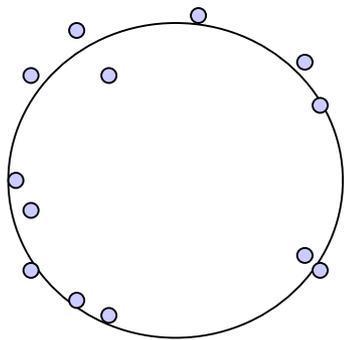
5

Nonlinear Regression with Optimization Method

Modeling with Least Square Eq.

- Find the proper Circle for the given points.
- Cost Function

$$\text{Model} : x^2 + y^2 = r^2$$



$$\begin{aligned}
 J &= J(x_0, y_0, r) \\
 &= \sum_i^N \left[(x_i - x_0)^2 + (y_i - y_0)^2 - r^2 \right]^2
 \end{aligned}$$

- $X_i = (x_i, y_i) \in R^2$

Minimizing Error with Gradient Descent method

- Gradient of J

$$\begin{aligned} J &= J(x_0, y_0, r) \\ &= \sum_i^N \left[(x_i - x_0)^2 + (y_i - y_0)^2 - r^2 \right]^2 \end{aligned}$$

$$\begin{aligned} \nabla J &= \nabla J(x_0, y_0, r) \\ &= \frac{\partial J}{\partial x_0} \hat{x}_0 + \frac{\partial J}{\partial y_0} \hat{y}_0 + \frac{\partial J}{\partial r} \hat{r} \end{aligned}$$

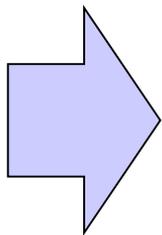
- Gradient Descent Method

$$\begin{aligned} P &= (x_0, y_0, r) \\ P_{k+1} &= P_k - \alpha \nabla J \end{aligned}$$

$$\begin{aligned} \nabla J = & \left(2 \sum_i^N \left[(x_i - x_0)^2 + (y_i - y_0)^2 - r^2 \right] \left[-2(x_i - x_0) \right] \right) \hat{x}_0 + \\ & \left(2 \sum_i^N \left[(x_i - x_0)^2 + (y_i - y_0)^2 - r^2 \right] \left[-2(y_i - y_0) \right] \right) \hat{y}_0 + \\ & \left(2 \sum_i^N \left[(x_i - x_0)^2 + (y_i - y_0)^2 - r^2 \right] \left[-2r \right] \right) \hat{r} \end{aligned}$$

$$P = (x_0, y_0, r)$$

$$P_{k+1} = P_k - \alpha \nabla J$$



$$x_0 |_{k+1} = x_0 |_k - \alpha \left(2 \sum_i^N \left[(x_i - x_0)^2 + (y_i - y_0)^2 - r^2 \right] \left[-2(x_i - x_0) \right] \right)$$

$$y_0 |_{k+1} = y_0 |_k - \alpha \left(2 \sum_i^N \left[(x_i - x_0)^2 + (y_i - y_0)^2 - r^2 \right] \left[-2(y_i - y_0) \right] \right)$$

$$r |_{k+1} = r |_k - \alpha \left(2 \sum_i^N \left[(x_i - x_0)^2 + (y_i - y_0)^2 - r^2 \right] \left[-2r \right] \right)$$

Example of GDM-based Regression

- randn : Normal distribution= $x \sim N(0,1)$
- Our distribution with $x' \sim N(\mu, \sigma)$
 - In Matlab code: circle1.m

$$x' \sim N(\mu, \sigma) = \mu + \sigma \cdot \text{randn}$$

Ex) Radius=20
Sigma =2

```
% generate data
N=100;

rm=20;
rs=2;

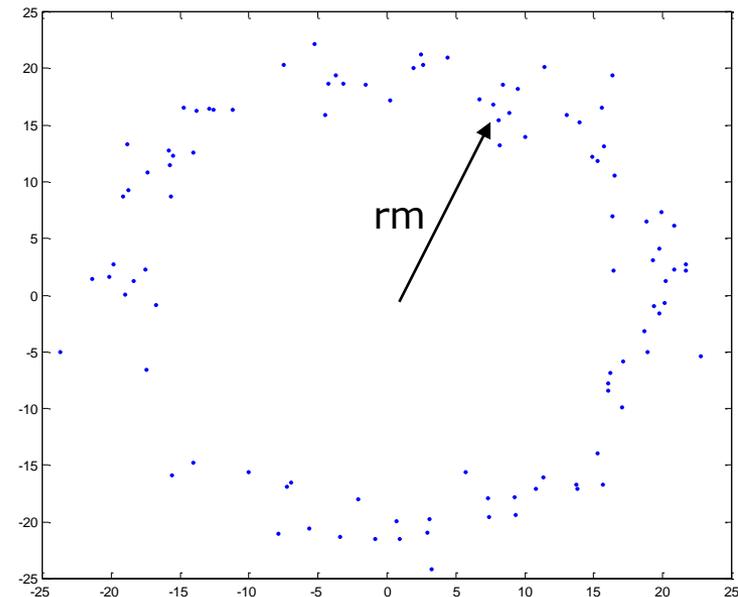
qm=0
qs=360;

r= rm+ randn(N,1)*rs;
q= qm+ randn(N,1)*qs;

x=[r,q];

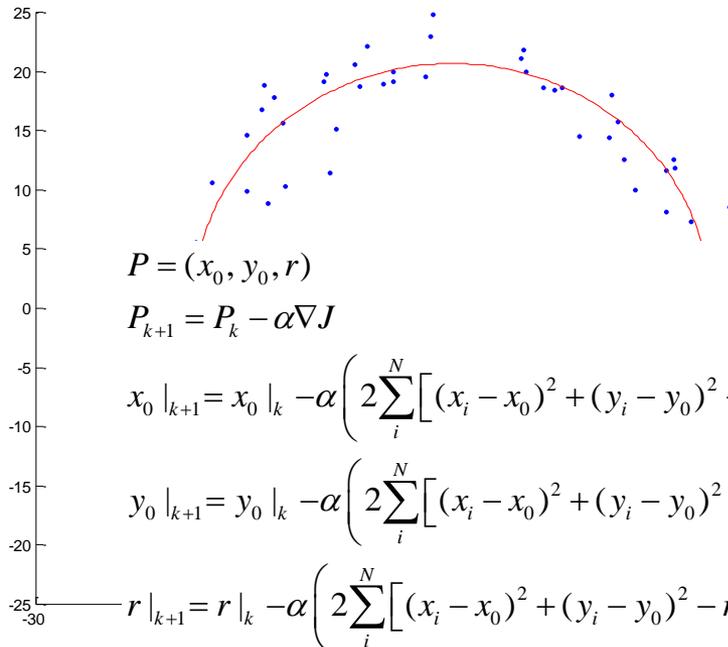
X=[ r.*cos(q.*pi/180), r.*sin(q.*pi/180)]

figure(1)
clf
plot(X(:,1),X(:,2),'.')
```



Example of GDM-based Regression

- GDM for finding x_0, y_0, r
- (circle2.m)



```

clear

%generate data
test1

% X:data
% for test, X=X+(3,0)
X(:,1)=X(:,1)+3;

% Exact x=3, y=0, r=20

x=0;
y=0;
r=0.1;
alpha=1e-6;

for i=0:100
    dx = X(:,1)-x;    % (xi-x)
    dy = X(:,2)-y;    % (yi-y)

    sumx=0;
    sumy=0;
    sumr=0;
    for j=1:N
        sumx = sumx+2*(dx(j)^2+dy(j)^2-r*r)*(-2)*dx(j);
        sumy = sumy+2*(dx(j)^2+dy(j)^2-r*r)*(-2)*dy(j);
        sumr = sumr+2*(dx(j)^2+dy(j)^2-r*r)*(-2)*r;
    end

    dJ_dx = sumx;
    dJ_dy = sumy;
    dJ_dr = sumr;

    x=x-alpha*dJ_dx;
    y=y-alpha*dJ_dy;
    r=r-alpha*dJ_dr;

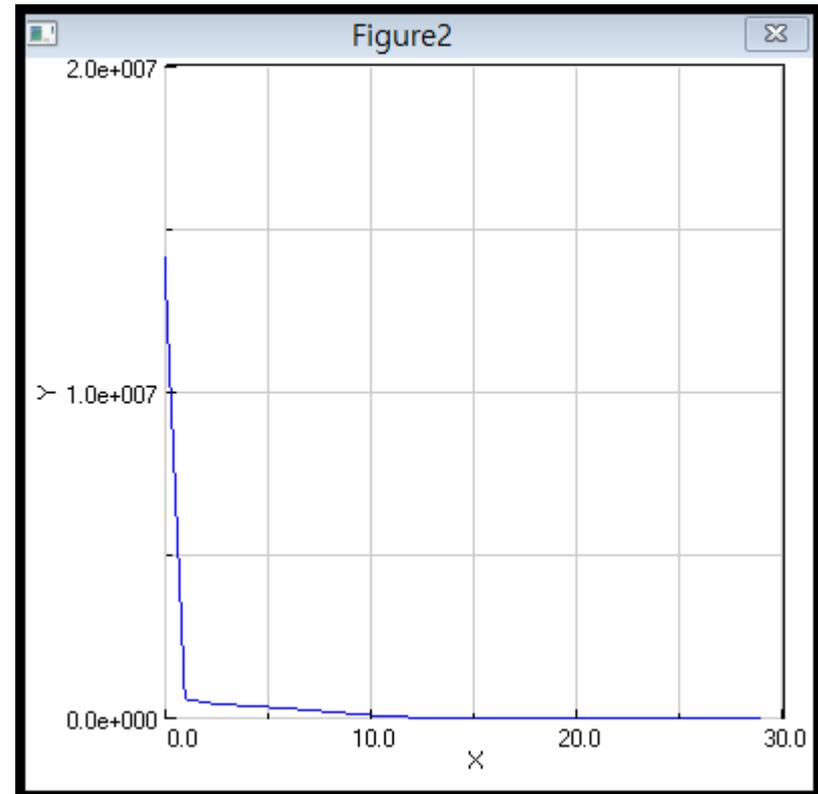
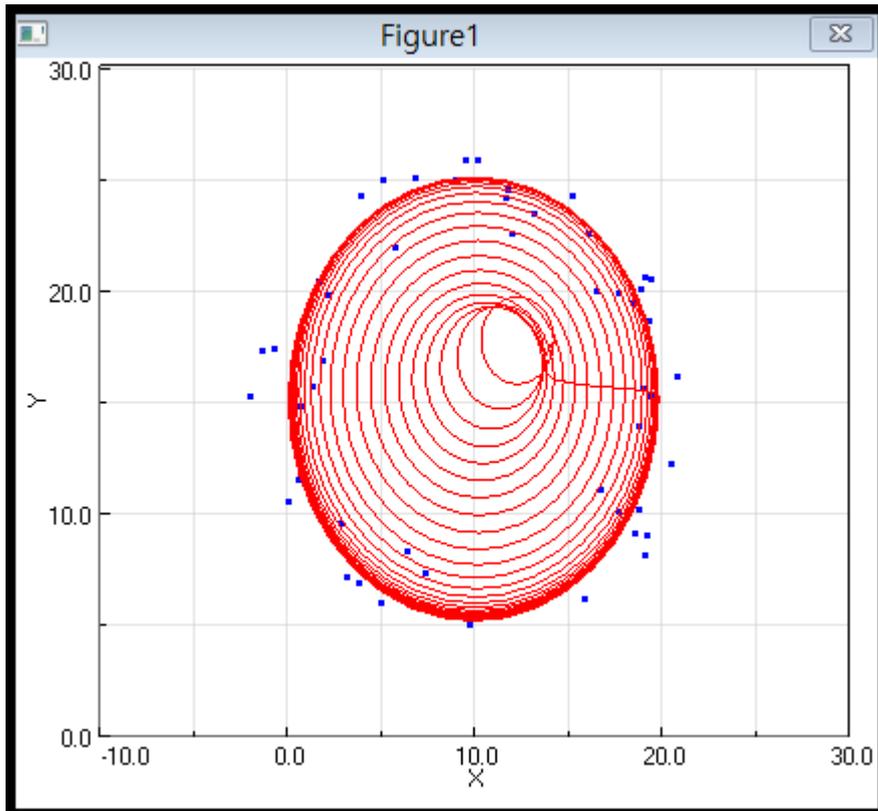
    % calc error
    J = (dx'*dx+dy'*dy-N*r*r)^2;

    if (J<1e-4)
        break;
    end

    [i,J,x,y,r]
end

```

I5regcircle

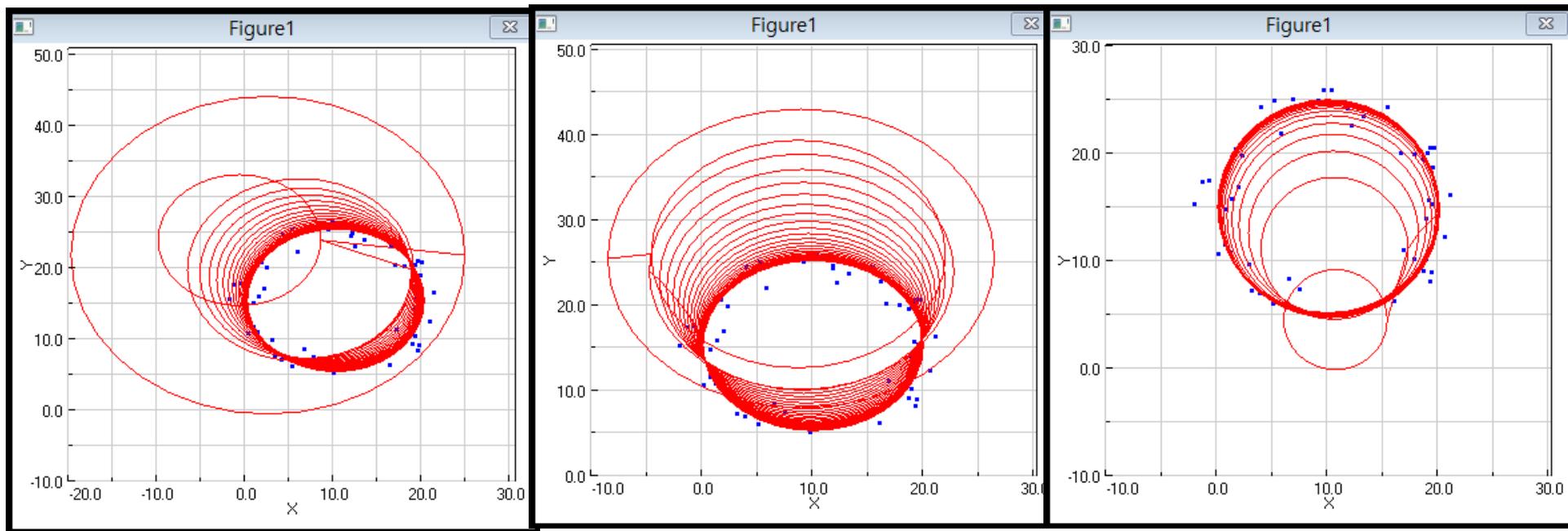


ex/ml/I5regcircle
I5regcircle.test(0,0,1)

Experiment:
Let's try many initial guesses.

Test(0,0,1) test(20,20,50) , etc.

Various Initial Guess



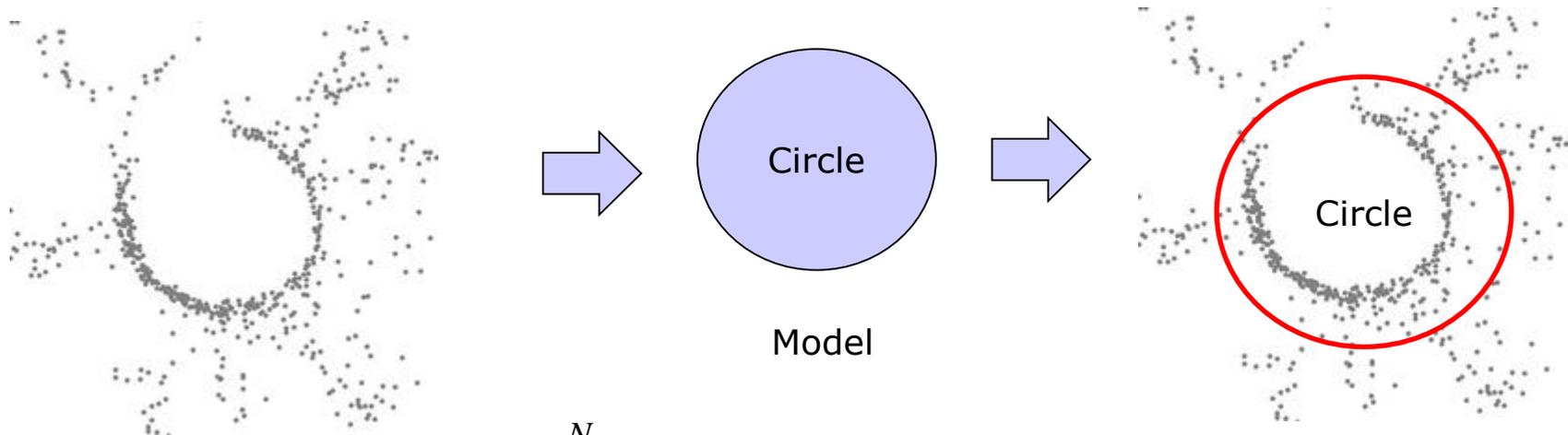
Large error of initial guess makes bad effects?

Try `test(0,0,100)` or `test(100,0,1)`

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Stochastic Regression (RANSAC)

Regression has the Problem like this

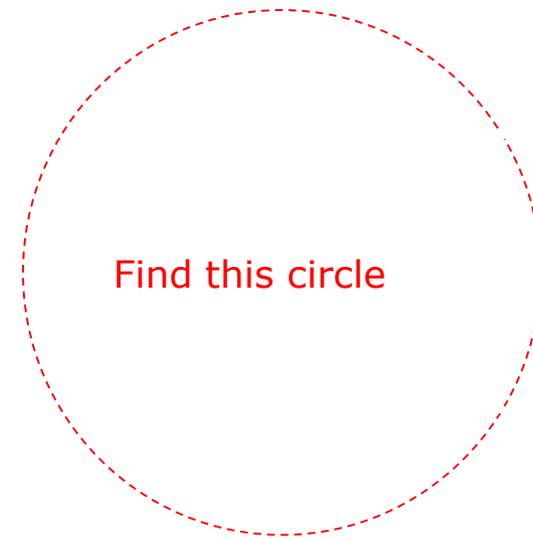
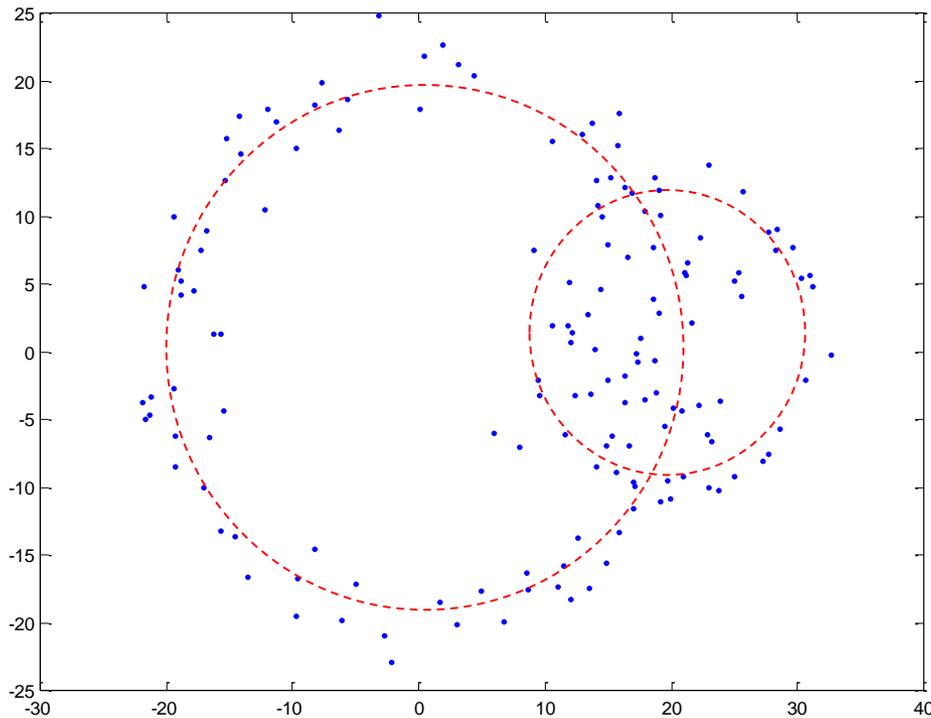


$$J = \sum_i^N \| (x_i - a)^2 + (y_i - b)^2 - r^2 \|^2$$

- Regression is Model-based method
- **The given DATA is NOT a circle**
- Thus, our model is wrong for data
 - **However, the data is a kind of Circles...**

Generate Non Circle Data

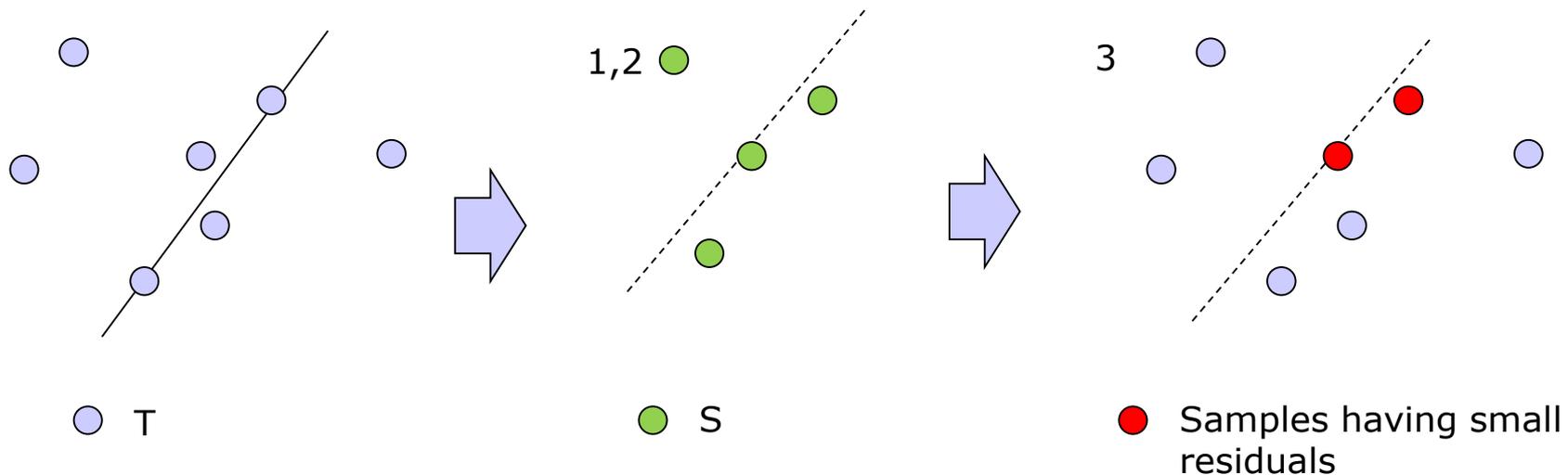
- Circle3.m generate two overlapped circles



RANSAC

- RANSAC
 - Random Sample Consensus
 - Pick Good sample from data and Throw away bad sample.
- Training set, T is given
- Pseudo code of RANSAC
 - 1. Take a random Sample, S of size m from T .
 - 2. Build a model, J with S
 - 3. Compute error, e of J with all data T
 - 4. if $|e| < \text{threshold}$, add S or small residuals into consensus set, CS
 - 5. repeat to 1 until CS is larger than some value.

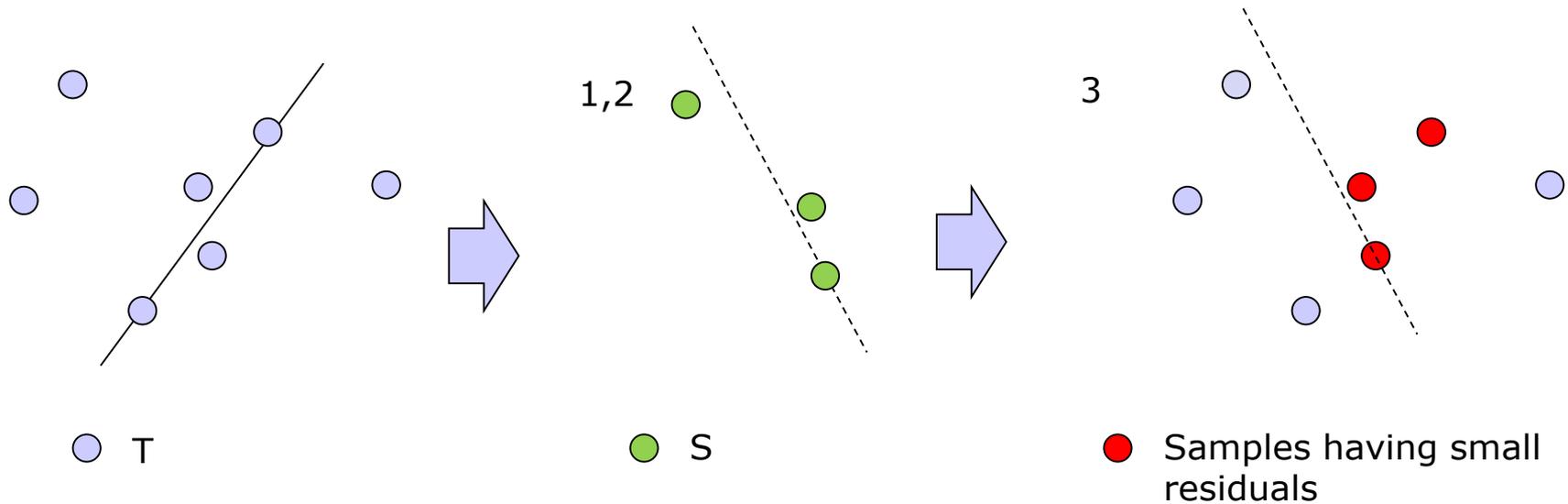
Pseudo Code of RANSAC 1



Pseudo code of RANSAC

1. Take a random Sample, S of size m from T .
2. Build a model, J with S
3. Compute error, e of J with all data T
4. if $|e| < \text{threshold}$, add S or small residuals into consensus set, CS
5. repeat to 1 until CS is larger than some value.

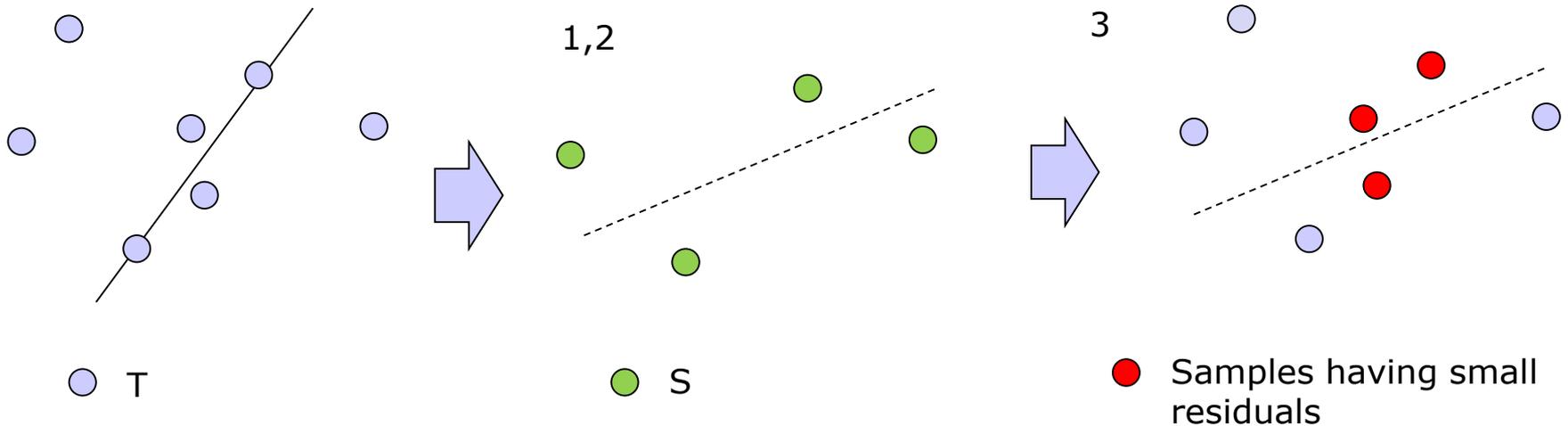
Pseudo Code of RANSAC 2



Pseudo code of RANSAC

1. Take a random Sample, S of size m from T .
2. Build a model, J with S
3. Compute error, e of J with all data T
4. if $|e| < \text{threshold}$, add S or small residuals into consensus set, CS
5. repeat to 1 until CS is larger than some value.

Pseudo Code of RANSAC 3



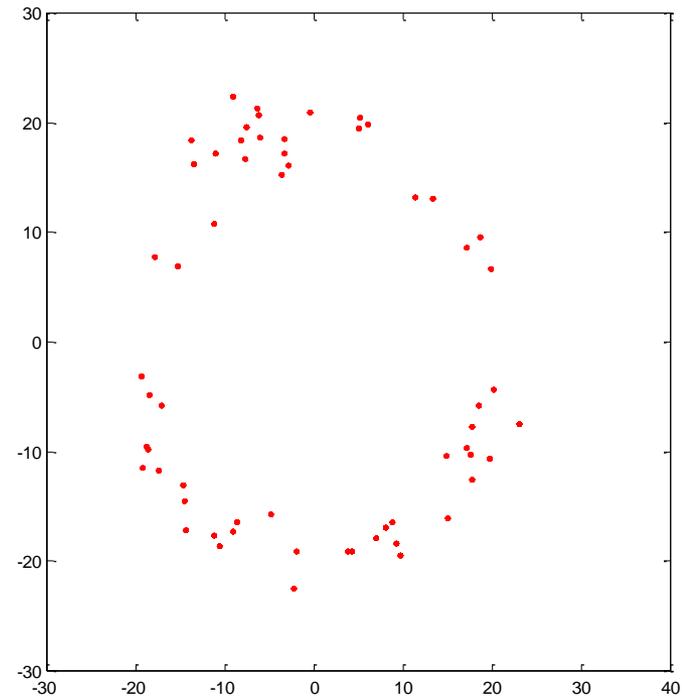
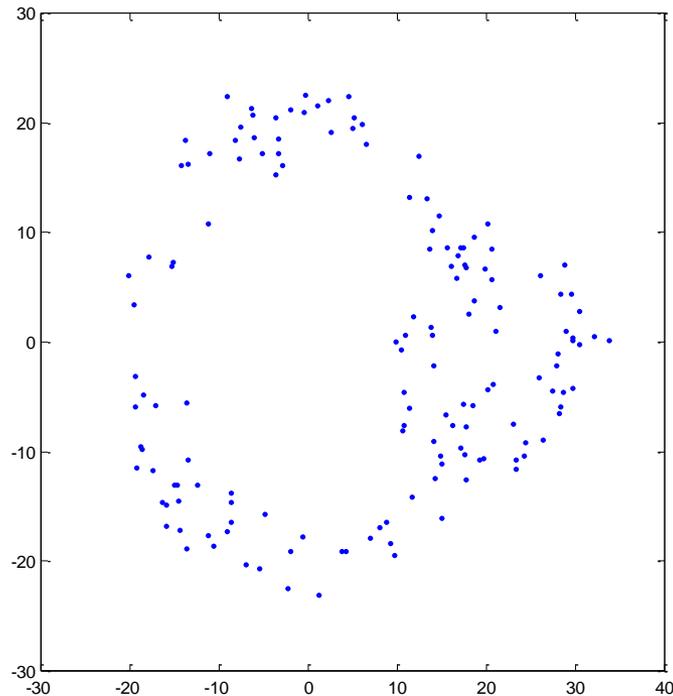
It does NOT satisfy
 $|e| < \text{threshold}$, then no
 residual is NOT added into
 CS

Pseudo code of RANSAC

1. Take a random Sample, S of size m from T .
2. Build a model, J with S
3. Compute error, e of J with all data T
4. if $|e| < \text{threshold}$, add S or small residuals into consensus set, CS
5. repeat to 1 until CS is larger than some value.

Circle3 and Circle4.m

- Circle3: generate Overlapped circle
- Circle4: Simple RANSAC



Test4.m

```
clear

%generate data
test3

Ns = 60; %SAMPLE
Xi = zeros(Ns,1);
Xin = [];

for i=0:30
    % get sample,Xs
    for j=1:Ns
        Xi(j) = ceil(rand*Ns);
    end
    Xs = X(Xi,:);

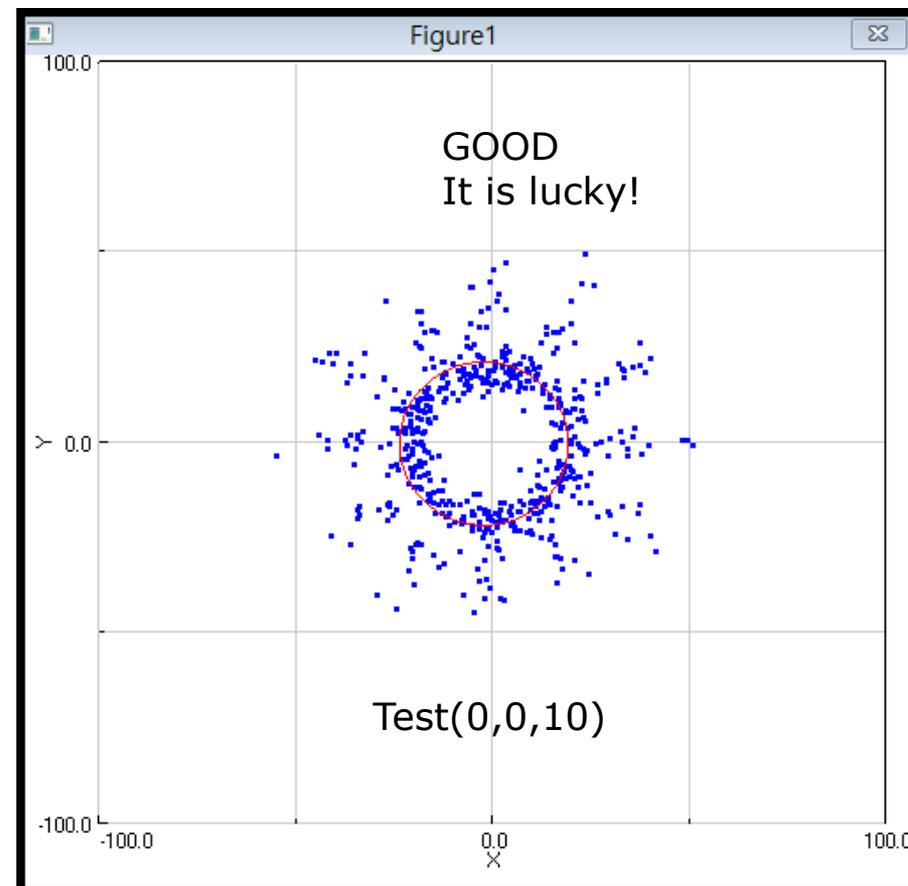
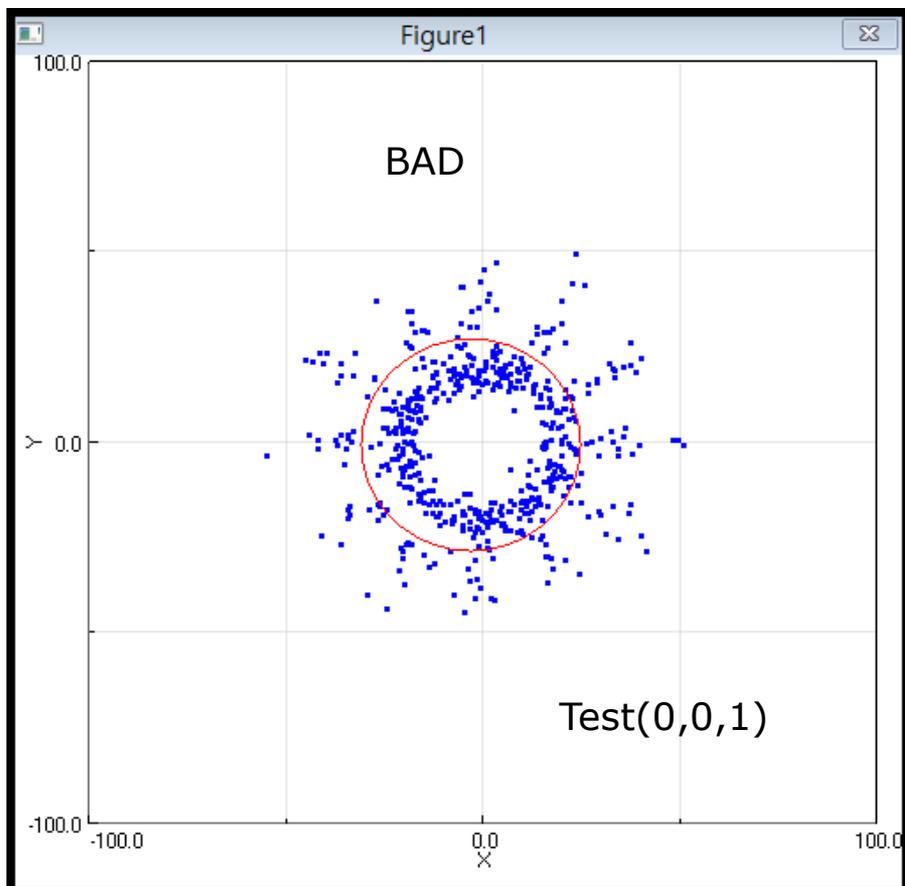
    %find circle from sample
    [J,x,y,r] = fcircle(Xs);

    if (J<1e-2)
        Xin = [Xin;Xs];
    end
end

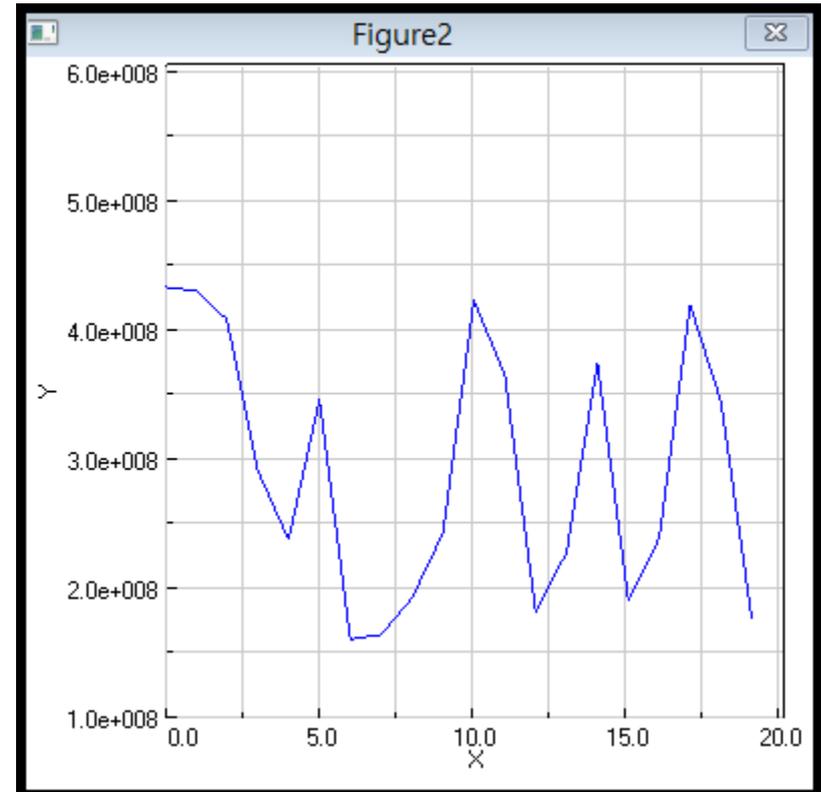
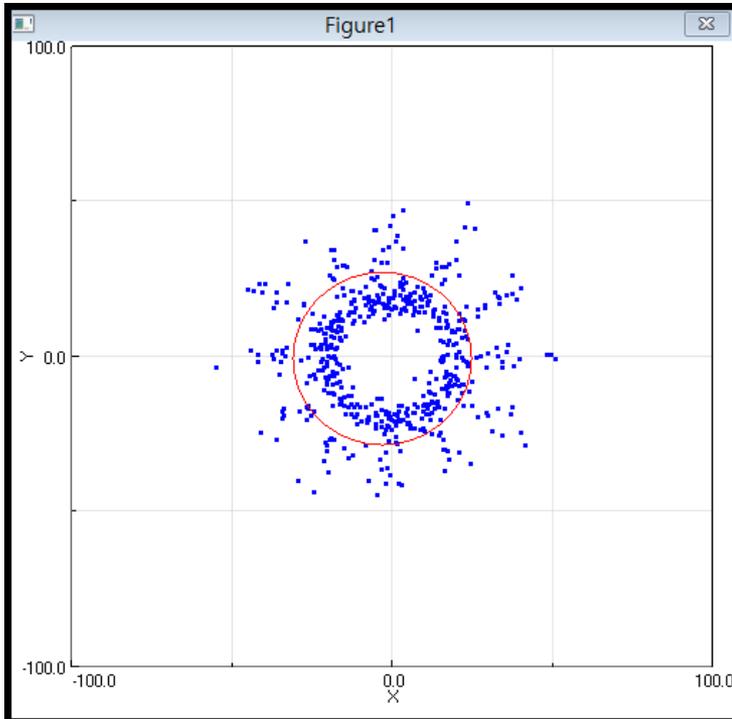
figure(2);
clf;
subplot(121)
plot(X(:,1),X(:,2),'.');
axis([-30 40 -30 30]);
subplot(122)
plot(Xin(:,1),Xin(:,2),'r.');
```

RANSAC: Why it is so useful?

- I5regransac.py DOES NOT use RANSAC



See Iteration Error Graph

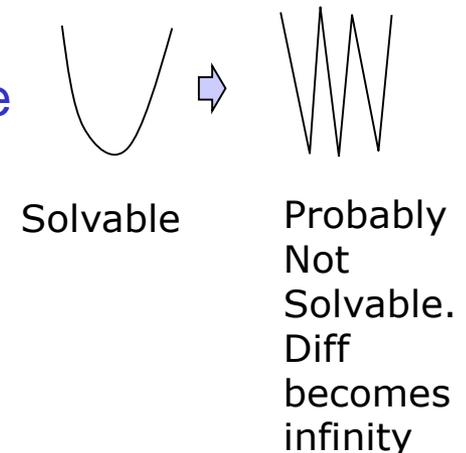


- Is it GOOD? Remind Convex Hulls.

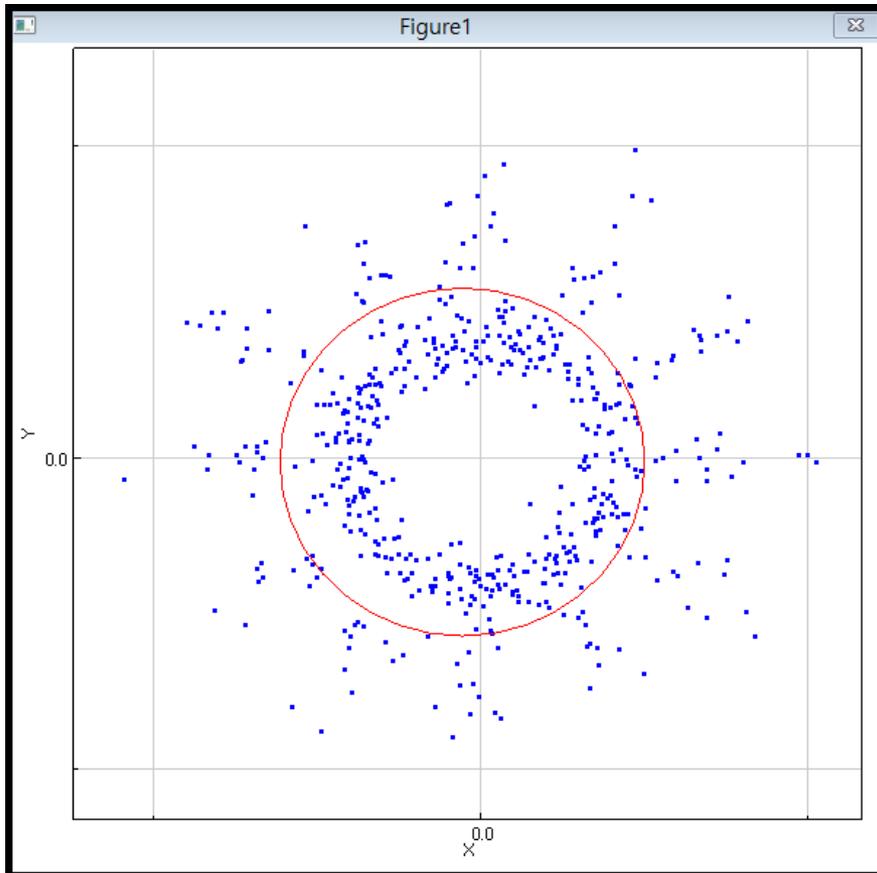
Test with Various Initial guess

What kinds of Problems occur?

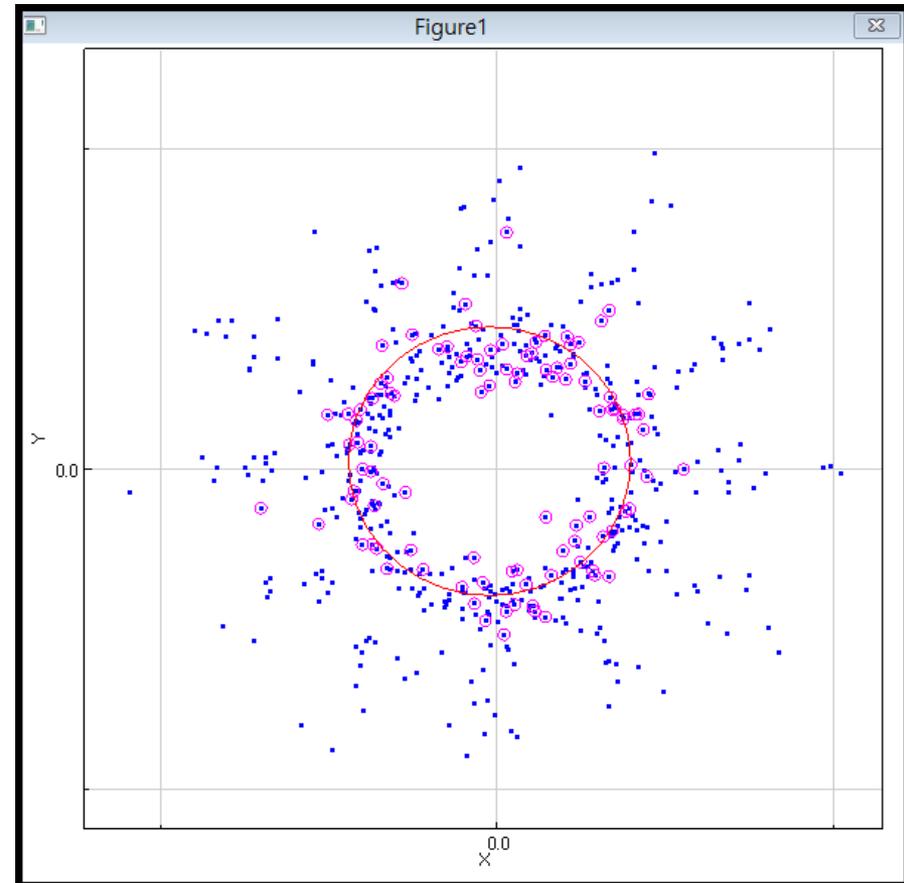
- 1. Too sensitive to Initial guess.
 - Regression method cannot satisfy circle + noise simultaneously.
 - Thus, It becomes UNSTABLE
- 2. In other words, Convex hulls are not so strong
 - l2regcircle shows good stability
 - However, l2regransac shows poor performance
 - Convex hull in this example was so sharp
 - Think differentiation leads to the optimal value



Comparison with RANSAC



Without RANSAC
l5regransac.test(0,0,1)



With RANSAC
l5regransac2.test()

l5regransac2.py

- edit ex/ml/l5regransac2
- l5regransac2.test()

```
def test():
    load()
    cs = findcs()

    #draw cs
    lg.figure(1)
    lg.graph(2)
    for i in range(0,len(cs)):
        s = cs[i]
        x = data[s][0]
        y = data[s][1]
        lg.plot(x,y,'mo')

    # run regression with cs
    if (len(cs)==0):
        print("No CS")
        return;
    xc = 0;
    yc = 0;
    r = 1;
```

Load 2d point data

l5regransac2.data →
[-9.76,16.2], [-6.88,-19.6],....

Get CS by RANSAC

cs = findcs()

cs is the INDEX of data
cs=[51,28,2,20,53,...]

Therefore,
Good sample is
data[cs[0]]
data[cs[1]]
data[cs[2]]
...



findcs : find good sample set= CS

```

def findcs():
    S=[]
    CS=[]
    ndata = len(data)
    for k in range(0,1000):
        # generate random sample
        sample=[]
        m= 20;
        for i in range(0,m):
            s = lm.randint(ndata)
            sample.append(s)

        # add sample into CS
        if (reg(sample)==True):
            s = len(sample)
            n = len(CS)

            for i in range(0,s):
                bExist = False
                for j in range(0,n):
                    if (CS[j]==sample[i]):
                        bExist = True

                if (bExist==False):
                    CS.append(sample[i])

            # if CS>taget number
            if (len(CS)>100):
                break
    return CS

```

Do sampling 1000 times

Number of sampling,
m=20

Larger m
or
Smaller m
?

1. Data number is 544
2. Sample number is m
3. Chose randint(544)
0, 1, 100, 200, 45, or 543
4. sample=[120, 3, ...]
5. reg() is a regression
Function with sample.

Reg() tries to find a good
solution



HW. RANSAC Performance

- findcs() runs $N=1000$ times sampling with $m=20$
- HW. 1 :
 - If we increase or decrease N , what happens?
 - Explain why it occurs
- HW. 2:
 - If we increase $m=20$, what happens?
 - Explain why it occurs
- HW. 3: reg() function has stop condition,

```
err = J(sample,xc,yc,r)
if (err<4e6):
    return True;
```

if we increase error threshold, $4e6$,
what happens?